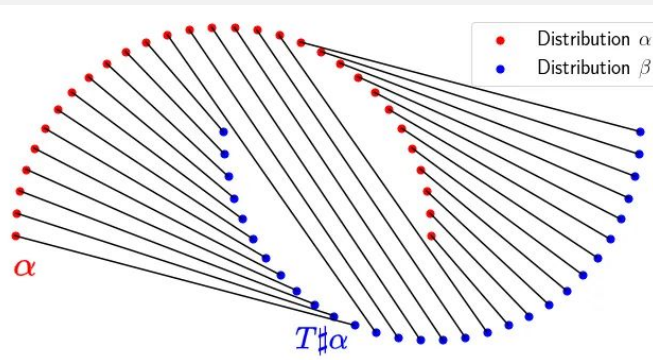


## Optimal Transport

Given two distributions, optimal transport (OT) seeks to move mass of distribution  $\alpha$  to distribution  $\beta$  in a way that minimizes work (or cost).



More formally, in the case of 2-Wasserstein distance, we find a map  $T : \mathbb{R}^n \rightarrow \mathbb{R}^n$  pushing  $\alpha$  to  $\beta$  such that  $T\# \alpha = \beta$  minimizes work.

$$W_2(\alpha, \beta)^2 := \min_T \int \|T(x) - x\|^2 d\alpha$$

### Exact OT: Linear Program

$$\begin{aligned} \min_{\gamma \in \Pi(a,b)} \quad & \langle \gamma, \mathbf{C} \rangle_F \\ \text{s.t.} \quad & \gamma \mathbf{1} = \mathbf{a} \\ & \gamma^T \mathbf{1} = \mathbf{b} \\ & \gamma \geq 0 \end{aligned}$$

a : Source  
b: Target  
C: Cost Matrix

Solving this LP is costly!  $O(n^3 \log(n))$

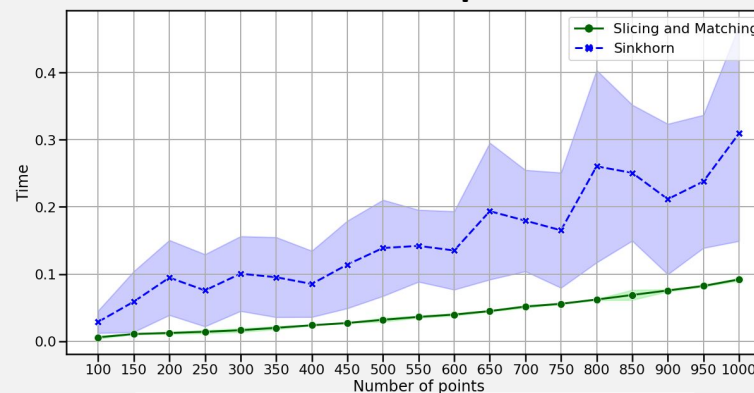
## Stochastic Slicing and Matching

### Algorithm 1 Slicing and Matching

```

1: procedure PITIE_AVG(Source  $X \in \mathbb{R}^{n \times d}$ , Target  $Y \in \mathbb{R}^{n \times d}$ ,  $K$ )
2:   for  $k = 1$  to  $K$  do
3:      $t(k) \leftarrow \frac{k + \log(k)}{K}$ 
4:     Sample random orthogonal matrix  $P \sim$  Haar distribution
5:      $P \leftarrow [\theta_1, \theta_2, \dots, \theta_d]$ 
6:     Initialize  $C$  such that  $C \in \mathbb{R}^{n \times d}$ 
7:     for  $p = 1$  to  $d$  do
8:        $X_{proj} \leftarrow X \cdot \theta_p$ 
9:        $Y_{proj} \leftarrow Y \cdot \theta_p$ 
10:      Solve Optimal Transport in 1D between  $X_{proj}$  and  $Y_{proj}$ 
11:      Find  $\sigma = \sigma_{Y_{proj}} \circ \sigma_{X_{proj}^{-1}}$  (mapping from  $X_{proj}$  to  $Y_{proj}$ )
12:       $C_p \leftarrow [(1 - t(k)) \cdot X_{proj}] + [t(k) \cdot Y_{proj} \# \sigma]$ 
13:    end for
14:    Update  $X \leftarrow P \cdot C$ 
15:  end for
16: end procedure
    
```

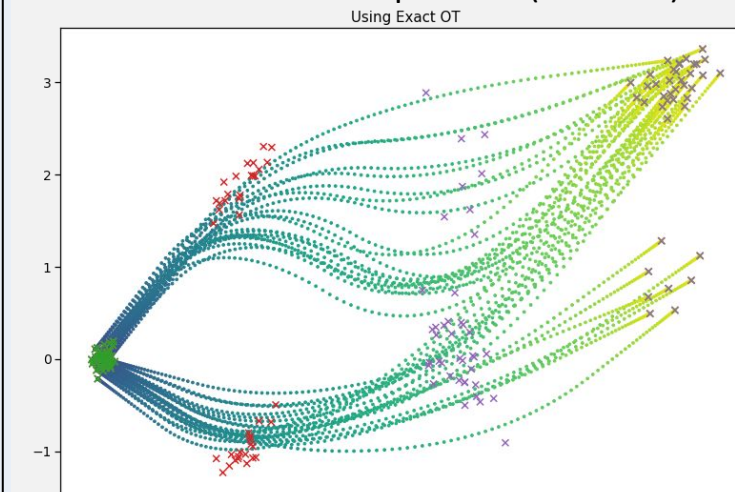
## Runtime Comparisons



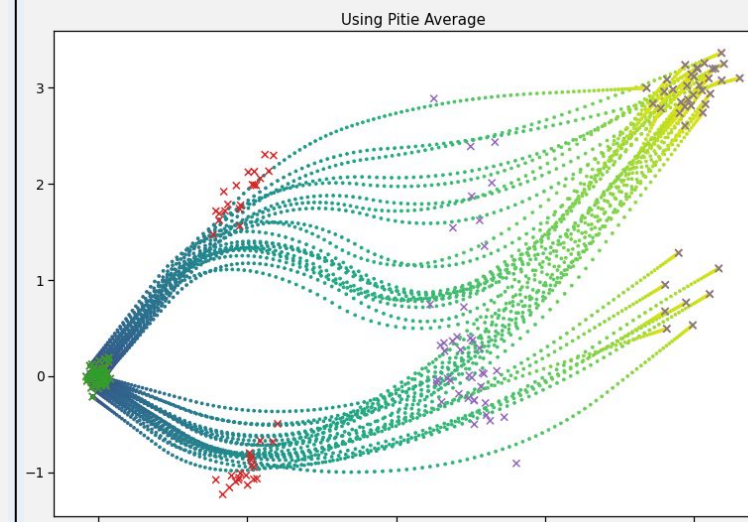
Method	Avg. Time (seconds)
Exact OT (LP)	16.427 ± 1.012
Sinkhorn + Ent. Reg.	0.1515 ± 0.077
Slicing + Matching	0.0407 ± 0.002

## Preliminary Results and Future Work

### Point Cloud Interpolation (Exact OT)



### Point Cloud Interpolation (Slicing + Matching)



References:

Gabriel Peyré; Marco Cuturi, Computational Optimal Transport: With Applications to Data Science, 2019.  
François Pitié, Anil C. Kokaram, Rozenn Dahyot, "Automated colour grading using colour distribution transfer", Computer Vision and Image Understanding, Volume 107, Issues 1–2, 2007, Pages 123–137 ISSN 1077-3142